

Graph

A data structure $G(V, E)$

V : vertices

every edge $e \in E$

is in form (v_i, v_j)

where $v_i, v_j \in V$

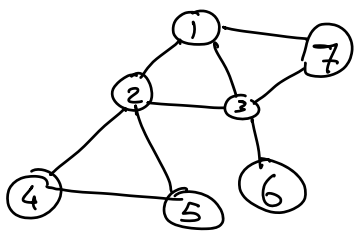
directed
↳ Twitter following

Undirected
↳ Facebook friends

weighted
↳ edges have weights
↳ map edges

Unweighted
↳ Facebook friends

$G(V, E)$



$$V = \{1, 2, \dots, 7\}$$

$$E = \{(1, 2), \dots, (3, 7)\}$$

degree of a node:

edges incident to the node

$$\deg(3) = 4, \deg(6) = 1$$

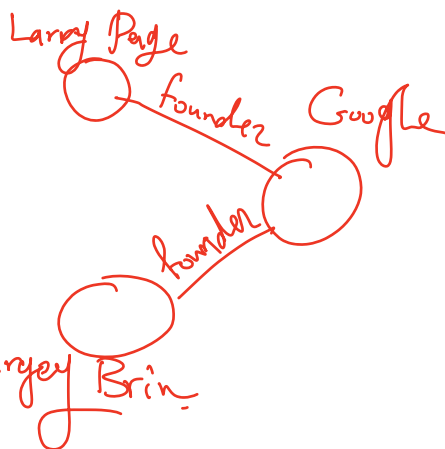
weighted Graphs

↳ edges / vertices have
Labels / properties

Knowledge Graphs

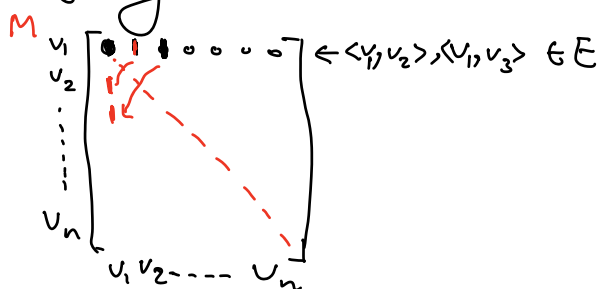
Vertices: objects

edges: relation b/w obj°



Graph Representation

Adjacency Matrix



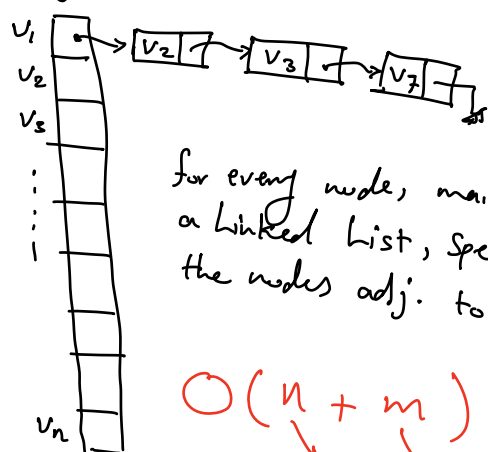
$$M[i, j] = \begin{cases} 1 & (v_i, v_j) \in E \\ 0 & \text{otherwise} \end{cases}$$

Observation: if the Graph is not
directed $\Rightarrow$ Storing the upper-Triangl
of the Matrix is enough

Requires $O(n^2)$ Space

Checking ^{the} existence of an edge $O(1)$

Adj. List



for every node, maintain a linked list, specifying the nodes adj. to it.

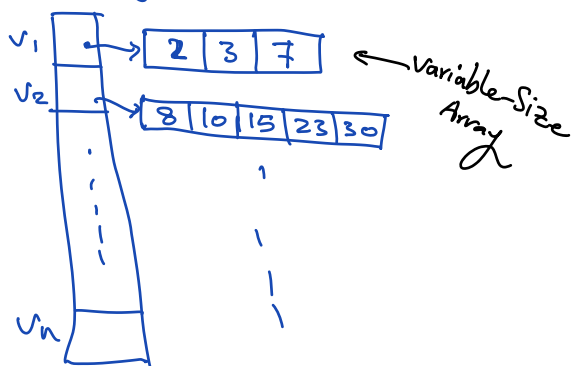
$O(n + m)$
 $\swarrow \searrow$
 $\# \text{ vertices} \quad \# \text{ edges}$

- It saves space

- $O(h)$ to check the existence of an edge
 $\hookrightarrow O(\text{max degree of nodes})$

Access $O(\log n)$

Storage $O(n + m)$



does $(v_2, v_{17}) \in E$

Path: a sequence of vertices

$\langle v_{i1}, v_{i2}, \dots, v_{ik} \rangle$ where

$\forall j \in [1, k-1],$

$\langle v_{ij}, v_{ij+1} \rangle \in E$

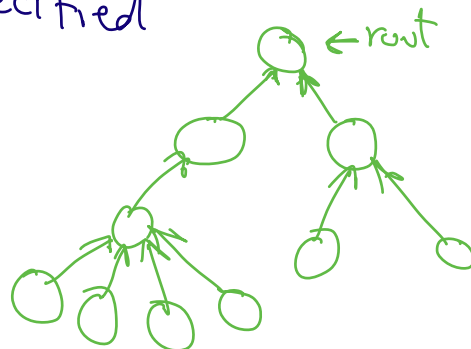
Simple Path: a path where no vertex is repeated more than once.

Cycle: a path where

$v_{i1} = v_{ik}$

Tree: a graph with no Cycle

Rooted Tree: a Tree where a node is specified as root and from every node in the tree the direction to root is specified



Connectivity in graph

- S-t Connectivity:
if there exists a path
from node s to node t
- S-t Shortest path:
the path with min length
from s to t
- Connected Component:
a subgraph G' , where
 $\exists v_i, v_j \in G', v_i$ is connected
to v_j .

Graph Traversal

Breadth first Search (BFS)

Depth first Search (DFS)

